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Armature Gear Layout  
Potentiometer  $e_i(t)$   
Desired azimuth angle  
input Differential  
amplifier and power  
amplifier Motor  
Schematic Desired  
azimuth angle input  
 $e_i(t)$  n-turn  
potentiometer  $80(t)$

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Azimuth angle output

Differential

preamplifier Power

amplifier  $v_p(t)$   $e_a(t)$

$V_i(t) + v_o(t) - kg \cdot m^2 \text{ N-}$

$m \text{ s/rad V-s/rad N-m/A}$

$n \dots$

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